Contents

1 **Basic Properties of Control Systems** 1
1.1 Basic Definitions 1
1.2 Systems Given by Differential Equations 8
1.3 Some Control-Theoretic Notions 13
1.4 Control Flow and Control Sets 16
1.5 Linearization and Regular Trajectories 34
1.6 Comments and Bibliographical Notes 42

2 **Introduction to Invariance Entropy** 43
2.1 Definitions and Basic Properties 43
2.2 Elementary Properties 49
2.3 A One-Dimensional Linear Example 66
2.4 Relations to Topological Feedback Entropy 68
2.5 Relations to Minimal Data Rates 78
2.6 Comments and Bibliographical Notes 86

3 **Linear and Bilinear Systems** 89
3.1 Linear Systems 90
3.2 Inhomogeneous Bilinear Systems 96
3.3 Comments and Bibliographical Notes 105

4 **General Estimates** 107
4.1 Upper Bounds of Ito-Type 107
4.2 Lower Bounds in Terms of Volume Growth Rates 117
4.3 Comments and Bibliographical Notes 120

5 **Controllability, Lyapunov Exponents, and Upper Bounds** 121
5.1 The Upper Bound Theorem for Control Sets 122
5.2 Approximation Results for Lyapunov Exponents 137
5.3 Comments and Bibliographical Notes 150

6 **Escape Rates and Lower Bounds** 151
6.1 Escape Rates and Invariance Entropy 151
6.2 The First Lower Bound Theorem 153

6.3 The Second Lower Bound Theorem 167
6.4 Comments and Bibliographical Notes 175

7 Examples 177
7.1 One-Dimensional Control-Affine Systems 177
7.2 Uniformly Expanding Systems 184
7.3 Inhomogeneous Bilinear Systems Revisited 192
7.4 Projective Systems 202
7.5 Comments and Bibliographical Notes 219

A General Concepts 221
A.1 Linear and Multilinear Algebra 221
A.2 Differentiable Manifolds 225
A.3 Carathéodory Differential Equations 236
A.4 Metric Spaces 242

B Dynamical Systems 245
B.1 Chain Recurrence and Chain Transitivity 245
B.2 Vector Bundles and Linear Flows 247
B.3 Dimension Theory and Topological Entropy 252
B.4 Additive and Subadditive Cocycles 261

References 263

Index 269